

# RDCZ9

RESIDENTIAL FAN  
SPEED CONTROLLER

## Modbus register map



## MODBUS REGISTER MAP

INPUT REGISTERS						
		Data type	Description	Raw data	Values	
1	Output value	unsigned integer	Output value in % Us	0–100	50 =	50 % Us
2	Output step	unsigned integer	Current step selected	0–9	8 =	step 8
3	Output Voltage	unsigned integer	Output voltage	0–2.300	1.150 =	115,0 VAC
4	Minimum output value	unsigned integer	Minimum output value	0–2.300	1.035 =	103,5 VAC
5	Maximum output value	unsigned integer	Maximum output value	0–2.300	2.300 =	230,0 VAC
6	Input voltage	unsigned integer	Input voltage rating in VAC	110–230	230 =	230 VAC
7	Input frequency	unsigned integer	Input frequency in Hz	50–60	50 =	50 Hz
8	Output overwrite mode	unsigned integer	Overwrite mode active	0, 1	0 =	Manual Overwrite
9–10			Reserved, return 0			

**Note:** The input registers can be read via the Modbus command: “Read input registers”.

### HOLDING REGISTERS

		Data type	Description	Raw data	Values	Factory default values
1	Device slave address	unsigned integer	Modbus device address	1–247		1
2	Modbus baud rate	unsigned integer	Modbus communication baud rate	0–6	0 = 4.800 1 = 9.600 2 = 19.200 3 = 38.400 4 = 57.600 5 = 115.200 6 = 230.400	2
3	Modbus parity mode	unsigned integer	Modbus parity check mode	0–2	0 = 8N1 1 = 8E1 2 = 8O1	1
4	Device type	unsigned integer	Device type: Read only	3.010	RDCZ9 = 3.010	
5	HW version	unsigned integer	Hardware version of the device (read only)	XXXX	0x0110 = HW version 1.1	
6	FW version	unsigned integer	Firmware version of the device (read only)	XXXX	0x0510 = FW version 5.1	
7–8			Reserved, return 0			
9	Output steps		Number of output steps defined	0–9	0 = 1% per step 1 = 1 step 8 = 8 steps	0
10	Start step		Starting step	0–9	0 = step 0	0
11	Minimum output value	unsigned integer	Set minimum value of output signal	30–65	45 = 45 % Us	45
12	Maximum output value	unsigned integer	Set maximum value of output signal	75–100	80 = 80 % Us	100
13	Overwrite mode	unsigned integer	Selection of overwrite mode	0, 1	0 = Inactive 1 = Active	0

HOLDING REGISTERS							
		Data type	Description	Raw data	Values	Factory default values	
14	Override value	unsigned integer	Output value in overwrite mode in percentage	30–100	50 = 50%		50
15	Kickstart	unsigned integer	Kickstart or softstart mode	0, 1	0 = Softstart 1 = Kickstart		0
16	Kickstart time	unsigned integer	Time for kickstart to run on maximum output voltage	2–10	5 = 5 s		5
17	Run / Standby	unsigned integer	Selection of Run / Standby mode	0, 1	0 = Run 1 = Standby		0
18	Start output value	unsigned integer	Start level output value when switched on	30–100	50 = 50 % Us		50
19			Reserved, returns 0				
20	Network Bus Termination Resistor (NBT)	unsigned integer	Set unit as first or last unit of the line by connecting network termination resistor	0, 1	0 = Disconnected (NBT open) 1 = Connected (NBT connected)		0
21	Master / Slave mode	unsigned integer	Master or slave mode selection	0, 1	0 = Slave mode 1 = Master mode		0
22	Temperature Setpoint	unsigned integer	Temperature setpoint value	0–700	200 = 20,0 °C		200
23	CO <sub>2</sub> setpoint	unsigned integer	CO <sub>2</sub> setpoint value	0–2.000	700 = 700 ppm		700
24	TVOC setpoint	unsigned integer	TVOC setpoint value	0–9.900	100 = 100 ppb 2.000 = 2.000 ppb		100
25	Pressure setpoint	unsigned integer	Pressure setpoint value	0–4.000	100 = 100 Pa 2.000 = 2.000 Pa		100

## HOLDING REGISTERS

		Data type	Description	Raw data	Values	Factory default values
26	Relative humidity setpoint	unsigned integer	Relative humidity setpoint value	0—1.000	400 = 40,0 % rH	400
27			Reserved, returns 0			
28	Sensor range	unsigned integer	Connected sensor measurement range	50—500	50 = 5,0°C (T) 50 = 50 Pa (P) 100 = 10,0 % rH (rH)	
29	PI control	unsigned integer	Enable PI-control	0, 1	0 = Disabled 1 = Enabled	0
30	PI control: Kp value	unsigned integer	Proportional gain for PI-control	0—50	20 = 2,0	20
31	PI control: Ki value	unsigned integer	Integration time for PI-control	0—50	20 = 0,2 s	20
32			Reserved, returns 0			
33	Display mode	unsigned integer	Shows either input or output values on the display during startup	0, 1	0 = Input value 1 = Output value	0
34	Output overrule timer	unsigned integer	Time for output overwrite value in HR 14 to be stopped	10—120	10 = 10 min 120 = 120 min	10
35—40			Reserved, return 0			

**Note:** The holding registers can be managed via the following Modbus commands: “Read Holding Registers”, “Write Single Register” or “Write Multiple Registers”.

The free Sentera configuration and monitoring software 3SModbus can be downloaded via: <https://www.sentera.eu/en/3SMCenter>