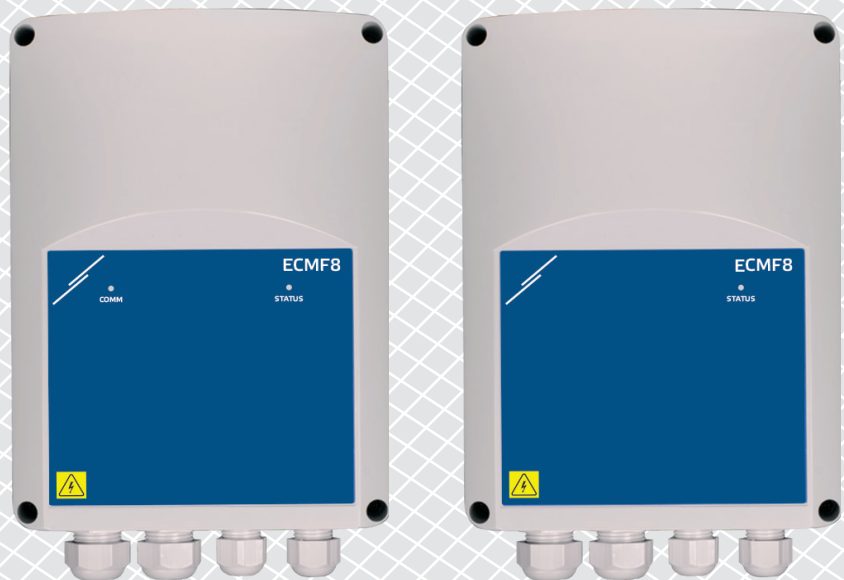


ECMF8 | HVAC CONTROLLER FOR EC FANS / VFD

Modbus register map



MODBUS REGISTER MAP

| INPUT REGISTERS | | | | | |
|-----------------|-------------------------------------|---------------|---|-----------|--|
| | | Data type | Description | Data | Values |
| 1 | Analogue / Modulating input 1 value | unsigned int. | Measured input value 1 when voltage / current / PWM/ digital input selected | 0—1.000 | 600 = 60,0% 1000 = 100,0 % |
| 2 | Analogue input 1 frequency | unsigned int. | Measured input 1 frequency in PWM mode | 0-8.000 | 8.000 = 8,000 Hz |
| 3 | AO1 output value | unsigned int. | Output Value of AO1 | 0 - 1.000 | 100 = 10% Output |
| 4 | AO1 Output type | unsigned int. | Output type of AO1 | 0—3 | 0 = OFF 1 = Voltage 2 = Current 3 = PWM |
| 5 | TI 1 Measured RPM | unsigned int. | Measured RPM Input 1 | 0 - 10000 | 0 = Stop or signal loss 100 RPM |
| 6 - 10 | | | Reserved, returns 0 | | |
| 11 | Analogue / Modulating input 2 value | unsigned int. | Measured input value 2 when voltage / current / PWM | 0 - 1000 | 600 = 60,0 % 1000 = 100,0 % |
| 12 | Analogue input 2 frequency | unsigned int. | Measured input 1 frequency in PWM mode | 0 - 8000 | 8000 = 8,000 Hz |
| 13 | AO2 output value | unsigned int. | Output Value of AO2 | 0 - 1000 | 100 = 10 % Output |
| 14 | AO2 output type | unsigned int. | Output type of AO2 | 0 - 3 | 0 = OFF 1 = Voltage 2 = Current 3 = PWM |
| 15 | TI 2 Measured RPM | unsigned int. | Measured RPM Input 2 | 0 - 10000 | 0 = Stop or signal loss 100 RPM |
| 16-29 | | | Reserved, returns 0 | | |
| 30 | Device State | unsigned int. | Device status | 0 - 65535 | Bit 3: Tacho input 2 error - (0 = OK, 1 = Fault) Bit 2: Tacho input 1 error - (0 = OK, 1 = Fault) Bit 1: Sensor 2 (outside) communication status (0 = OK, 1 = Lost) Bit 0: Sensor 1 (outside) communication status (0 = OK, 1 = Lost) |

Note: The input registers can be read via the Modbus command: "Read input registers".

| HOLDING REGISTERS | | | | | | | |
|-------------------|--------------------------------------|---------------|--|--|----------------|--|--|
| | | Data type | Description | Raw data range | Default values | Values | |
| 1 | Device slave address | unsigned int. | Modbus device address | 1 - 247 | 1 | | |
| 2 | Modbus baud rate | unsigned int. | Modbus communication baud rate | 0 - 6 | 2 | 0 = 4.800 1 = 9.600 2 = 19.200 3 = 38.400 4 = 57.600 5 = 115.200 6 = 230.400 | |
| 3 | Modbus parity | unsigned int. | Parity check mode | 0-2 | 1 | 0 = 8N1 1 = 8E1 2 = 8O1 | |
| 4 | Device type | unsigned int. | Device type (Read only) | ECMF8-AO-DM = 2108 ECMF8-AO-WF = 2109 ECMF8-AO-EW = 2110 | | | |
| 5 | HW version | unsigned int. | Hardware version of the device (Read only) | XXXX | | 0 x 0100 = | HW version 1.0 |
| 6 | FW version | unsigned int. | Firmware version of the device (Read only) | XXXX | | 0 x 0100 = | FW version 1.0 |
| 7 | | | Reserved, returns 0 | | | | |
| 8 | Modbus Time Out | unsigned int. | Time Out Of Modbus, after which the output is set to OFF | 0 - 60 | 0 | 0 = 1 = 60 = | Time Out - Min Value 1 min 60 min |
| 9 | Modbus network bus termination (NBT) | unsigned int. | Set device as end device of the line / or not by connecting NBT | 0 - 1 | 0 | 0 = 1 = | disconnected connected |
| 10 | Modbus registers reset | unsigned int. | Resets Modbus Holding registers to default values. When finished this register is automatically reset to '0' | 0 - 1 | 0 | 0 = 1 = | Idle Reset Modbus Registers |
| 11 | Control type input 1 | unsigned int. | Input control type of output 1 | 0 - 1 | 0 | 0 = 1 = | Single input (In1) Differential input (In1 - In2) |
| 12 | Input source output 1 | unsigned int. | Input source selection for output 1 | 0 - 2 | 0 | 0 = 1 = 2 = | Analogue / Modulating input Modbus Overwrite |

| HOLDING REGISTERS | | | | | | | |
|-------------------|-------------------------------------|---------------|---|----------------|----------------|--|--|
| | | Data type | Description | Raw data range | Default values | Values | |
| 13 | | | Reserved, returns 0 | | | | |
| 14 | Analogue/Modulating input 1 | unsigned int. | Analogue/Modulating Input type selection | 1 - 4 | 1 | 1 = 0 - 10 VDC 2 = 0 - 20 mA 3 = PWM 4 = Digital | |
| 15-16 | | | Reserved, returns 0 | | | | |
| 17 | Control type output 1 | unsigned int. | Output 1 control type | 0 - 1 | 0 | 0 = Output 1 1 = Output 1 and 2 | |
| 18 | Minimum output 1 | unsigned int. | Output 1 minimum value | 200 - 600 | 200 | 300 = 30% 600 = 60% | |
| 19 | Maximum output 1 | unsigned int. | Output 1 maximum value | 600 - 1.000 | 1.000 | 600 = 60% 1.000 = 100% | |
| 20 | Value overwrite output 1 | unsigned int. | Value overwrite for output 1 | 0 - 1.000 | 0 | 0 = OFF 400 = 40% 1.000 = 100% | |
| 21 | Off level Output 1 | unsigned int. | Off level Output 1 | 0-400 | 0 | 0 = 0% 400 = 40% | |
| 22 | Output 1 Inverse mode | unsigned int. | Inverse mode output 1 | 0 - 1 | 0 | 0 = Disabled 1 = Enabled | |
| 23 | Analogue / Modulating Output 1 mode | unsigned int. | Output type Analogue / Modulating output 1 | 0 - 3 | 1 | 0 = OFF 1 = Voltage 2 = Current 3 = PWM | |
| 24 | AO1 PWM Voltage Source selection | unsigned int. | AO1 PWM voltage source | 0 - 1 | 0 | 0 = +12 VDC 1 = Open Collector | |
| 25 | PWM Frequency | unsigned int. | Select the PWM frequency of the outputs AO1 and AO2 | 1 - 8 | 1 | 1 = 1 kHz 2 = 2 kHz 3 = 3 kHz 4 = 4 kHz 5 = 5 kHz 6 = 6 kHz 7 = 7 kHz 8 = 8 kHz | |
| 26 | Tacho Input 1 Enable | unsigned int. | Tacho Input 1 enable / disable. | 0 - 1 | 0 | 0 = Disable 1 = Enable | |

| HOLDING REGISTERS | | | | | | | |
|-------------------|-----------------------------------|---------------|--|----------------|----------------|--------------------------|--|
| | | Data type | Description | Raw data range | Default values | Values | |
| 27 | Tacho Input 1 Setup | unsigned int. | Setup number of pulses per revolution for tacho signal of the motor / fan. | 1 - 100 | 1 | 10 = | 10 pulses per revolution |
| 28-30 | | | Reserved, returns 0 | | | | |
| 31 | Control type input 2 | unsigned int. | Input control type of output 2 | 0 - 1 | 0 | 0 = 1 = | Single input (In2) Differential input (In2 - In1) |
| 32 | Input source output 2 | unsigned int. | Input source selection for output 2 | 0 - 2 | 0 | 0 = 1 = 2 = | Analogue / Modulating input Modbus Overwrite |
| 33 | | | Reserved, returns 0 | | | | |
| 34 | Analogue/ Modulating input 2 mode | unsigned int. | Analogue/Modulating Input type selection | 1 - 4 | 1 | 1 = 2 = 3 = 4 = | 0 - 10 VDC 0 - 20 mA PWM Digital |
| 35-36 | | | Reserved, returns 0 | | | | |
| 37 | Control type output 2 | unsigned int. | Output 2 control type | 0 - 1 | 0 | 0 = 1 = | output 2 output 2 and 1 |
| 38 | Minimum output 2 value | unsigned int. | Output 2 minimum value | 100 - 600 | 200 | 300 = 600 = | 30% 60% |
| 39 | Maximum output 2 value | unsigned int. | Output 2 maximum value | 600 - 1.000 | 1.000 | 600 = 1.000 = | 60% 100% |
| 40 | Output overwrite 2 value | unsigned int. | Value overwrite for output 2 | 0 - 1.000 | 0 | 0 = 400 = 1.000 = | OFF 40% 100% |
| 41 | Off level Output 2 | unsigned int. | Off level output 2 | 0 - 400 | 0 | 0 = 400 = | 0% 40% |
| 42 | Output 2 Inverse mode | unsigned int. | Inverse mode output 2 | 0 - 1 | 0 | 0 = 1 = | Disabled Enabled |

HOLDING REGISTERS

| | | Data type | Description | Raw data range | Default values | Values |
|-------|-------------------------------------|---------------|--|----------------|----------------|--|
| 43 | Analogue / Modulating Output 2 mode | unsigned int. | Output type Analogue / Modulating output 2 | 0 - 3 | 1 | 0 = OFF 1 = Voltage 2 = Current 3 = PWM |
| 44 | AO2 PWM Voltage Source selection | unsigned int. | AO2 PWM voltage source | 0 - 1 | 0 | 0 = +12 VDC 1 = Open Collector |
| 45 | | | Reserved, returns 0 | | | |
| 46 | Tacho Input 2 Enable | unsigned int. | Tacho Input 2 enable / disable. | 0 - 1 | 0 | 0 = Disabled 1 = Enabled |
| 47 | Tacho Input 2 Setup | unsigned int. | Setup number of pulses per revolution for tacho signal of the motor / fan. | 1 - 100 | 1 | 10 = 10 pulses per revolution |
| 48-51 | | | Reserved, returns 0 | | | |
| 52 | LED's brightness control | unsigned int. | The intensity of LED 2 | 0 - 10 | 5 | 0 = 0% 1 = 10% 2 = 20% 3 = 30% 4 = 40% 5 = 50% 6 = 60% 7 = 70% 8 = 80% 9 = 90% 10 = 100% |
| 53-60 | | | Reserved, returns 0 | | | |

Note: The holding registers can be managed via the following Modbus commands: "Read Holding Registers", "Write Single Register" or "Write Multiple Registers".

The free Sentera configuration and monitoring software 3SModbus can be downloaded via: <https://www.sentera.eu/en/3smcenter>

